

Univerzitet u Nišu
Prirodno-matematički fakultet
Departman za računarske nauke

Predmet:

Internet pametnih uređaja

Praktična vežba:

Primeri programa

Cilj vežbe:**Opis vežbe:**

U okviru ove vežbe student je u obavezi da realizuje sledeće aktivnosti:

- 1.0 Razvoj i testiranje programa za kontrolu LED
- 2.0 Razvoj i testiranje programa za povezivanje na WiFi
- 3.0 Razvoj i testiranje programa za očitavanje adrese DS18S20

1.0 Razvoj i testiranje programa za kontrolu LED

Varijanta programa za razvojne ploce sa klasicnom LED:

```
#define LED 2 // ovde treba staviti broj esp32 pin-a na koji je vezana dioda

void setup(void) {
    pinMode(LED,OUTPUT); // Set pin mode

    Serial.begin(115200);
    Serial.printf ("Setup finised.\n");
}

void loop(void) {
    delay(2000);
    digitalWrite(LED, HIGH);

    Serial.printf ("Pali/gasi \n");

    delay(300);
    digitalWrite(LED, LOW);
}
```

Varijanta programa za razvojne ploce sa WS2812 LED. U ovom slucaju treba najpre u projekat dodati biblioteku FastLED nakon cega ce se u fajlu Platformio.ini pojaviti:

```
lib_deps = fastled/FastLED@^3.10.3
```

a sam program bi izgledao ovako:

```
#include "FastLED.h"

#define NUM_LEDS 1
#define DATA_PIN 21 // broj esp32 pin-a na koji je vezana WS281 dioda

CRGB leds[NUM_LEDS];

void setup()
{
    FastLED.addLeds<WS2812B, DATA_PIN, GRB>(leds, NUM_LEDS); // GRB ordering
is typical
    FastLED.setBrightness(50);
}

void loop()
{
    leds[0] = CRGB::Red;
    FastLED.show();
    delay(500);

    leds[0] = CRGB::Green;
    FastLED.show();
    delay(500);

    leds[0] = CRGB::Blue;
    FastLED.show();
    delay(500);

    leds[0] = CRGB::White;
    FastLED.show();
    delay(500);

    leds[0] = CRGB::Black;
    FastLED.show();
    delay(500);
}
```

Druga varijanta je da se koristi Adafruit_NeoPixel biblioteka za kontrolu WS2812 LED.

```
#include <Arduino.h>
#include <Adafruit_NeoPixel.h>
```

```

#define PIN_LED_RGB    21 // RGB LED is connected to the GPIO 21

// #define PORT_SERIAL USBSerial // Use USB for communication
#define PORT_SERIAL Serial // Use USB for communication
// #define PORT_SERIAL Serial0 // Use UART0 for communication
// #define PORT_SERIAL Serial1 // Use UART1 for communication

Adafruit_NeoPixel led (1, PIN_LED_RGB, NEO_GRB + NEO_KHZ800);

void setup() {
    PORT_SERIAL.begin (115200);
    delay (500);

    PORT_SERIAL.println ("Blink with ESP32-S3-Zero-S3FH4R2");
    led.begin();
}

void loop() {
    led.clear();

    // Cycle through the three colors.
    led.setPixelColor (0, led.Color (150, 0, 0));
    led.show();
    PORT_SERIAL.println ("RED");
    delay (500);

    led.setPixelColor (0, led.Color (0, 150, 0));
    led.show();
    PORT_SERIAL.println ("GREEN");
    delay (500);

    led.setPixelColor (0, led.Color (0, 0, 150));
    led.show();
    PORT_SERIAL.println ("BLUE");
    delay (500);
}

```

2.0 Razvoj i testiranje programa za povezivanje na WiFi

```

#include <Arduino.h>

#include <WiFi.h>

#define WIFI_SSID "????S"
#define WIFI_PASSWORD "??????"

// MAC addres
uint8_t baseMac[6];

```

```

char apName[] = "ada-xxxxxxxxxxxx";
char mac_adr [13];

void setup(void) {
    Serial.begin(115200);

    esp_read_mac(baseMac, ESP_MAC_WIFI_STA); // Get MAC address for WiFi
station

    sprintf (apName, "ada-%02X%02X%02X%02X%02X%02X", baseMac[0], baseMac[1],
baseMac[2], baseMac[3], baseMac[4], baseMac[5]);
    sprintf (mac_adr, "%02X%02X%02X%02X%02X%02X", baseMac[0], baseMac[1],
baseMac[2], baseMac[3], baseMac[4], baseMac[5]);

    WiFi.setHostname(apName);

    WiFi.mode(WIFI_STA);

    Serial.println("Connecting to Wi-Fi...");
    WiFi.begin(WIFI_SSID, WIFI_PASSWORD);

    while (WiFi.status() != WL_CONNECTED) {
        Serial.print('.');
        delay(1000);
    }

    Serial.println ();
    Serial.print ("IP adresa: ");
    Serial.println (WiFi.localIP());

    Serial.printf ("\nSetup završen.\n");
}

void loop (void) {

}

```

3.0 Razvoj i testiranje programa za očitavanje adrese DS18S20

```

#include <Arduino.h>
#include <OneWire.h>

#define SENSOR_PIN 23

OneWire ds(SENSOR_PIN);

void setup(void) {
    Serial.begin(115200);
    Serial.printf ("Setup završen.\n");
}

```

```
}

void loop(void) {

    byte i;
    byte present = 0;
    byte data[12];
    byte addr[8];

    ds.reset_search();

    if ( !ds.search(addr)) {
        Serial.print("Nema vise mogucih adresa.\n");
        ds.reset_search();
        return;
    }

    Serial.print("R=");

    for( i = 0; i < 8; i++) {
        Serial.print(addr[i], HEX);
        Serial.print(" ");
    }

    if ( OneWire::crc8( addr, 7) != addr[7]) {
        Serial.print("CRC nije validan!\n");
        return;
    }

    if ( addr[0] == 0x10) {
        Serial.print("Ovaj senzor pripada DS18S20 familiji.\n");
    }
    else {
        if ( addr[0] == 0x28) {
            Serial.print("Ovaj senzor pripada DS18B20 familiji.\n");
        }
        else {
            Serial.print("Ne moze se prepoznati familija senzora.: 0x");
            Serial.println(addr[0],HEX);
            return;
        }
    }

    ds.reset();
    ds.select(addr);
    ds.write(0x44,1); // start A/D konverzije

    delay(1000);      // 750ms je dovoljno

    present = ds.reset();
```

```
    ds.select(addr);

    ds.write(0xBE);    // citamo rezultat A/D konv

    Serial.print("P=");
    Serial.print(present,HEX);
    Serial.print(" ");

    for ( i = 0; i < 9; i++) {    // nama treba 9 bajtova
        data[i] = ds.read();
        Serial.print(data[i], HEX);
        Serial.print(" ");
    }

    Serial.print(" CRC=");
    Serial.print (OneWire::crc8( data, 8), HEX);
    Serial.println();
}
```